

# The Category of $X$ -Nets

What are Networks ???

Networks = Graphs ?

What are Networks ???

Networks = Metric Spaces !

Why ?

The *lengths* of edges

- is not only highly informative indicating the presumed relative time spans of evolutionary phases under investigation !
- more importantly: it is essential for many algorithms that are designed to searching for “network structures” whose edge lengths are “optimally” adapted to given data !

More specifically:

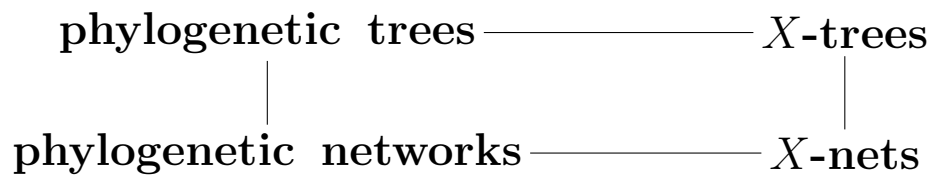
Our topic here is the structure of

*X*-nets:

A natural framework for taxonomic analysis in terms of *phylogenetic networks*

quite in analogy to *X-trees*

supporting taxonomic analysis in terms of (the much more familiar) *phylogenetic trees*.



## Outline

- **Picture Show**
- **Basic Terminology**
- **Basic Results**
- **$X$ -nets and  $\mathbb{R}$ -valued split systems**

## Basic Terminology

(i)  $\mathbf{M} = (M, D) : M \times M \rightarrow \mathbb{R} :$

$$(u, v) \mapsto uv$$

a (finite) metric space,

(ii) Intervals:  $u, v \in M :$

$$[u, v] = [u, v]_D :=$$

$$\{w \in M : uv = uw + wv\}$$

(iii) Parallel pairs:  $(u, u'), (v, v') \in M^2 :$

$$uu' \parallel vv' \iff$$

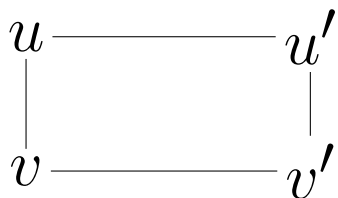
$$u', v \in [u, v'] \quad \text{and} \quad u, v' \in [u', v]$$

## Basic Terminology

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## Basic Terminology

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$$u', v \in [u, v'] \quad \text{and} \quad u, v' \in [u', v]$$

(iv) M an (abstract)  $L_1$ -space

$$\iff$$

“ $\parallel$ ” is an equivalence relation on  $M^2$

## Basic Terminology

(v) An **edge** in  $\mathbf{M}$  (or an **M-edge**) is a two-subset  $\{u, v\} \subseteq M$  with

$$\#[u, v] = 2.$$

$\Rightarrow$  Definition of **M-paths**:

A sequence  $a_0, a_1, a_2, \dots, a_k$  of point in  $\mathbf{M}$  is an **M-path** if all consecutive pairs  $\{a_{i-1}, a_i\}$  are **M-edges**

A sequence  $a_0, a_1, a_2, \dots, a_k$  of point in  $\mathbf{M}$  is a **geodesic M-path** if it is an **M-path** and one has

$$a_0 a_k = \sum_{i=1}^k a_{i-1} a_i$$

## Basic Terminology

(v) An **edge** in  $\mathbf{M}$  (or an **M-edge**) is a two-subset  $\{u, v\} \subseteq M$  with

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$\Rightarrow$  Fundamental for relating graphs and metric spaces!

## Basic Terminology

(v) An **edge** in  $\mathbf{M}$  (or an **M-edge**) is a two-subset  $\{u, v\} \subseteq M$  with

$$\#[u, v] = 2.$$

(vi)  $\mathbf{M}$  is **bipartite**  $\iff$

every edge  $\{u, v\}$  is a **gated** subset of  $\mathbf{M}$ ,

i.e.,  $\forall x \in M \quad \exists y = y(x) \in \{u, v\} :$

$\forall w \in [u, v] : xw = xy + yw$



## A Basic Result

A **net** is a bipartite  $L_1$ -space.

### Theorem 1

A metric space  $\mathbf{N}$  is a net  $\iff$  it can be embedded isometrically into a **hypercube**, i.e., a product

$$\mathbf{M} := \mathbf{M}_1 \times \mathbf{M}_2 \times \cdots \times \mathbf{M}_k$$

of a metric spaces of cardinality 2 so that any two points in  $\mathbf{N}$  can be connected by a geodesic path  $a_0, a_1, a_2, \dots, a_k$  in  $\mathbf{M}$  all of whose points are points in  $\mathbf{N}$ .

## Basic Terminology

A an  $X$ - **net** is a net  $\mathbf{N} = (N, D)$  together with a (labelling) map

$$\psi : X \rightarrow N$$

with the property that, for every point  $v \in N$  and any two edges  $e, e'$  in  $\mathbf{N}$ , there exists some  $x \in X$  such that  $v$  and  $\psi(x)$  can be connected by an  $\mathbf{N}$ -path not involving any edge that is parallel to either  $e$  or  $e'$ .

### A morphism

$$\varphi : \mathbf{N} = (N, D; \psi) \rightarrow \mathbf{N}' = (N', D'; \psi')$$

from an  $X$ -net  $\mathbf{N} = (N, D; \psi : X \rightarrow N)$  into an  $X$ -net  $\mathbf{N}' = (N', D'; \psi' : X \rightarrow N')$  is a map  $\varphi$  from  $N$  into  $N'$  such that

$$D'(\varphi(u), \varphi(v)) \leq D(u, v)$$

holds for all  $u, v \in N$ ,

$$D'(\varphi(u), \varphi(v)) + D'(\varphi(v), \varphi(w)) = D'(\varphi(u), \varphi(w))$$

holds for all  $u, v, w \in V$  with  $uv+vw = uw$ ,  $\{\varphi(u), \varphi(v)\}$  is an  $\mathbf{N}'$ -edge for every  $\mathbf{N}$ -edge  $\{u, v\}$  with  $\varphi(u) \neq \varphi(v)$ , and  $\psi' = \varphi \circ \psi$  holds.

## Basic Terminology

That is, morphisms are maps that are

**non-expansive** ( $D'(\varphi(u), \varphi(v)) \leq D(u, v)$ ),

**additive** or **interval-preserving** ( $v \in [u, w] \Rightarrow \varphi(v) \in [(\varphi(u), \varphi(w))]$ ),

**edge-preserving** ( $\{u, v\}$  an  $\mathbf{N}$ -edge and  $\varphi(u) \neq \varphi(v) \Rightarrow \{\varphi(u), \varphi(v)\}$  is an  $\mathbf{N}'$ -edge).

**and labelling-compatible** ( $\psi'(v) = \varphi(\psi(v))$ ) .

## More basic results

### Theorem 2

- (i) There exists at most one morphism from one  $X$ -net into another one.
- (ii) A morphism from one  $X$ -net into another one is an isometry if and only if both nets induce the same metric on  $X$ .
- (iii) For every  $X$ -net  $(\mathbf{N}, \psi)$ , there exists an  $X$ -net  $(\mathbf{N}, \psi)^*$ , also called the **injective hull** of  $(\mathbf{N}, \psi)$ , together with an isometric embedding  $\varphi_{(\mathbf{N}, \psi)}$  from  $(\mathbf{N}, \psi)$  into  $(\mathbf{N}, \psi)^*$  such that, for every isometric embedding  $\varphi$  of  $(\mathbf{N}, \psi)$  into another  $X$ -net  $(\mathbf{N}', \psi')$ , there exists a (necessarily unique) isometric embedding  $\varphi'$  from  $(\mathbf{N}', \psi)$  into  $(\mathbf{N}, \psi)^*$  with  $\varphi_{(\mathbf{N}, \psi)} = \varphi' \circ \varphi$ .
- (iv) The underlying metric space  $\mathbf{N}$  of  $X$ -net  $(\mathbf{N}, \psi)$  is a median metric space if and only if  $(\mathbf{N}, \psi)$  is its own injective hull.

# Main Theorem

- (i) Associating, to any edge  $e = \{u, v\}$  in an  $X$ -net  $(\mathbf{N}, \psi)$ , the  $X$ -split

$$S_e := \{A_{u < v}, A_{v < u}\}$$

whose two split halves  $A_{u < v}$  and  $A_{v < u}$  are those two subsets of  $X$  for which, for any  $x$  in  $A_{u < v}$  or  $A_{v < u}$ , respectively, the point  $\psi(x)$  is closer to  $u$  than to  $v$  or closer to  $v$  than to  $u$ , respectively, induces a **well-defined** and **injective** map from the set of equivalence classes of  $\mathbf{N}$ -edges of  $\mathbf{N}$  into the set  $\mathcal{S}(X)$  of **splits** of  $X$ .

- (ii) Associating, to any  $X$ -net  $(\mathbf{N}, \psi)$ , the map  $\mu = \mu_{(\mathbf{N}, \psi)}$  from  $\mathcal{S}(X)$  into  $\mathbb{R}$  that maps any split of the form  $S = S_e$  for some edge  $e = \{u, v\}$  in  $(\mathbf{N}, \psi)$  onto its **length**  $uv$ , and every other split of  $X$  onto 0, defines a **well-defined** map from the set of isomorphism classes of  $X$ -nets **onto** the set of all such maps.
- (iii) And one has  $\mu = \mu'$  for the maps  $\mu, \mu'$  associated with two  $X$ -nets  $(\mathbf{N}, \psi)$  and  $(\mathbf{N}', \psi')$  if and only if the injective hulls of these two nets are isomorphic objects in the category of  $X$ -nets.